- 1 Large Gaps in Monitoring Urban Air Pollution in the Majority World Due to Adverse
- 2 Economic and Political Conditions
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35 Abstract

36 Ambient air pollution has highly adverse effects on public health and the environment, particularly in urban areas of the Majority World. Systematic air quality 37 38 monitoring (AQM) is a precondition for effective policies to mitigate this problem, and 39 making AQM data publicly available also signals commitment to take action. Thus far, little 40 is known about the global capacity for public AQM, and how it varies across geographic 41 location, pollution exposure, and socio-economic characteristics. We thus constructed a 42 novel, geocoded dataset on AQM behavior in more than ten thousand urban areas of low to middle-income countries. In almost 90% of these urban areas, we are unable to identify any 43 44 monitoring activity, and the form and extent of AQM in the remaining 10% varies greatly. Income levels and characteristics of political institutions (democracy) turn out to be key 45 46 drivers of variation in AQM activity, with urban areas in more democratic countries more likely to respond with more AQM to high air pollution levels. The evidence provided here 47 48 can serve as a wake-up call for public authorities, international institutions, and civil society 49 stakeholders to invest far more than hitherto the case into AQM, particularly in under-50 monitored, less affluent, and less democratic settings. 51 52 Keywords 53 Air pollution; policy; air quality monitoring; lower income countries; Global South 54 55 **Synopsis**

Air quality monitoring in urban areas of lower income countries systematically varies across
geographic location, pollution exposure, and socio-economic characteristics.

58

59 Introduction

60 Ambient air pollution has deleterious effects on human health, the environment, and the economy worldwide. e.g. 1-6 Urban areas in low- to upper middle-income countries, which 61 we call the Majority World, face particularly serious problems in this realm due to rapid 62 63 population growth and expanding industrial activity.⁷ For instance, according to the Health Effects Institute⁸, air pollution is estimated to be the second leading risk factor for death in 64 65 Africa, following malnutrition, with more than one million estimated deaths in 2019 and around 14 percent of child deaths under age five linked to air pollution. 66 67 It is widely acknowledged that systematic air quality monitoring (AQM) is indispensable for effective clean air policy.⁹ Yet, the apparent shortage of data hampers not 68

69 only problem-solving efforts upfront. It also precludes continuous evaluation and

70 improvement of existing intervention strategies. Conversely, AQM that generates reliable,

71 publicly available information could enhance public awareness and support stronger action

against air pollution.^{10,11} As suggested by one recent study¹¹, the presence of AQM at US

raises in more than 40 cities may have contributed to lower air pollution levels in the

respective cities. And as succinctly noted by Harrington: "Measurement is the first step that

75 leads to control and eventually to improvement. If you can't measure something, you can't

76 understand it. If you can't understand it, you can't control it. If you can't control it, you can't

*improve it.*¹² Several studies observe, moreover, that policymakers gain or lose public

real support because of improving or deteriorating air quality, thus underscoring that AQM is

79 closely tied to processes of political accountability. e.g. 13,14

It is worth noting in this context that remote sensing data on air quality are becoming
more widely available, e.g. for fine particulate matter (PM2.5). However, their accuracy
remains disputed because ground-level pollution needs to be estimated from data on large air
columns, and their spatial and temporal resolution is widely regarded as insufficient for
designing and implementing well-targeted clean air policies.^{15–18}

Existing literature points to important monitoring gaps in the Majority World and suggests reasons for such gaps, but does not yet offer a systematic characterization of spatial patterns in AQM. ^{e.g. 2,7,19,20} As a consequence, systematic analysis of political, socioeconomic, and other drivers of variation in AQM is also missing.

89 Here we characterize spatial patterns of AQM throughout the Majority World and 90 identify potential drivers of variation in AQM, focusing on thousands of urban areas across 91 low- to upper middle-income countries, rather than countries as a whole. The reason is, that 92 aggregating AQM activity to the country level would blur differences between and within countries. Our analysis focuses on three key drivers of environmental policy preferences and 93 94 behavior, which are also presumed to influence behavior with regard to AQM. These are 95 economic resources, political institutions, as well as environmental problem pressure, and 96 responsiveness to it.

97 Economic resources are widely regarded as a key enabler of more stringent
98 environmental policies and, as a corollary, also environmental monitoring.^{10,21 22,23} According
99 to the hierarchy of needs argument²⁴, higher average income levels eventually induce more
100 public demand for cleaner air, and by implication also more demand for measuring air
101 quality. Moreover, higher income levels go hand in hand with more resources that are
102 potentially available for AQM. Both mechanisms are deeply intertwined and thus hard to

separate analytically because higher income levels are likely to induce both more demand for 103 104 AQM and capacity to meet this demand. One noteworthy recent development is that technological innovations are offering new opportunities for low-cost monitoring, which is 105 106 especially relevant in lower-income contexts, though much more expensive reference-grade monitors are still considered the 'gold standard' in AQM both for reliability and 107 regulatory/legal reasons.²⁷ Consequently, we distinguish between two types of AQM, 108 expecting monitoring activity to increase with income levels with this effect being more 109 110 pronounced for low-cost than for reference-grade AQM.

Previous studies highlight the impact of democratic institutions on environmental 111 policy choices and their outcomes. They provide both theoretical arguments and empirical 112 evidence in favor of the expectation that democratic political institutions make societies more 113 likely to implement more ambitious environmental policies and achieve higher levels of 114 environmental system quality. e.g. 28-31 On the demand side, democracy makes it easier for 115 116 scientists, citizens, civil society, and other stakeholders to identify environmental problems 117 and aggregate and organize various demands into ways and means that put pressure on 118 policymakers to act. On the supply side, in democracies, policymakers have stronger incentives to meet the demands of a broad range of citizens, relative to autocracies that tend 119 120 to be governed by a small elite.^{32,33} The key reason is that democratic policymakers need to be (re-)elected.^{34–37} We thus expect that demand and supply mechanisms are, jointly, likely to 121 result in a positive effect of democratic institutions on AQM. 122

As a corollary to the democracy argument, we also expect that urban areas are more likely to respond to higher pollution levels with more AQM in settings characterized by more democratic institutions. The reason is that, as air pollution increases, the issue is more likely to become politically salient in a democratic setting, and there is thus likely to be more pressure on policymakers to offer solutions to the problem. A first step towards such solutions is usually improved AQM.

129

130 Methods and Materials

131 <u>Unit of analysis</u>

To characterize the spatial distribution of monitoring activity, we construct a new dataset by geo-matching the location of monitoring stations from which air pollution data is reported with the coordinates of so-called Urban Centres (UC). These are urban centers housing a population of at least 50'000 and having a population density of 1'500 or more per square kilometer. To qualify as a UC, cities must also have commuting zones that are socioeconomically integrated into the city.^{41,43} We use UC and the term city synonymouslythroughout the paper.

Even though air pollution is widely regarded as having disproportionately negative effects on people in low-income countries,⁴⁴ current studies on clean air policies are strongly biased towards high-income countries, underscoring the need for a comprehensive analysis of lower-income nations^{9,45} where incomes are, on average, around four times lower than in highincome countries.⁴⁶ We therefore focus on UC in non-OECD countries and exclude highincome countries.

The complete dataset includes 11'106 UCs, most of them in India or China (see Fig. 1 and Fig. 2). To obtain a balanced dataset and avoid over-representing these two countries, we randomly subsample UCs from these two countries, resulting in 500 cities each for China and India, matching Ethiopia, the third-largest country in terms of UCs. This process yields a final dataset of 7'106 cities, of which 1'365 have at least one monitoring station. As a robustness check, we use different samples from the full dataset as well as the full dataset including all cities in China and India.

152 Data Sources

153 *Monitoring stations*

154 With UCs as the unit of analysis, we merge data on reported terrestrial AQM activity from three different sources with global coverage, monitoring any activity up to mid-April 155 156 2024. The databases differ in monitoring instruments, including (low-cost) air sensors and reference monitors, and coverage focus.^{38–40} The inclusion of all three sources ascertains that 157 we cover different parts of the world as well as different monitoring systems. While the Purple 158 Air source focuses on low-cost sensor monitoring stations, the WAQI and OpenAQ include 159 160 mostly reference-grade monitoring stations. Because the inclusion of PurpleAir sensors 161 extends our coverage to otherwise under-represented regions (South America, Africa), we 162 decided to include both types.

We are aware that not all AQM activities show up in OpenAQ, WAQI, or PurpleAir. For example, companies, local AQM campaigns, or specific countries might opt not to make their data publicly available. Furthermore, OpenAQ and WAQI are continuously adding new public reports of air pollution data, which need to be machine-accessible, adding technical barriers to what kinds of data are being ingested in these databases. Also, OpenAQ ingests data in raw units (e.g. μ g/m³ for PM_{2.5}), whereas WAQI compiles different pollutants into a comprehensive Air Quality Index, and can ingest such indices, which explains why these

datasets offer different spatial coverage. Differences in what gets added into OpenAQ and WAQI, as well as what is available in the PurpleAir database lead us to consider any AQM reporting in our analysis: various raw pollutants and Air Quality Index-related data. This allows us to cover any public AQM, which is what "ordinary" citizens would access to inform themselves about the air quality where they live. We are confident that our dataset is representative of the publicly available AQM data around the globe.

We identify 68 monitors placed at US embassies and exclude them from the main analysis because the installation of such monitors is exogenous to the drivers we wish to explore in our analysis.

179 *Economic resources*

180 Economic resources are measured using the Gross Domestic Product (GDP) per capita (p.c.) of each UC for the year 2015, as provided in the OECD dataset. The database enumerates GDP 181 estimates computed using global figures for the annual total GDP based on purchasing power 182 parity (PPP) within the Urban Centre 2015, denominated in US dollars (base year 2007). As 183 184 these figures are accessible at a 30 arc-second resolution (about 1 km at equator), it enables us to use information on GDP for each city and not only on a standardized country level.⁴⁷ To 185 186 capture the prosperity of an UC, not influenced by its size, the variable is divided by the 187 population size in the same year (2015), which results in the GDP p.c. of an UC. Inspecting the OECD dataset, we found that there are 314 out of 11'106 UCs with a GDP PPP value of 0, 188 189 which is unrealistic. 151 of these UCs are situated in Ethiopia or India. Given that none of these UC has an observable monitoring station, we opt to exclude these 314 entities. Also, the 190 191 average PM_{2.5} level across the UCs differs only very little (0.012µg higher average PM_{2.5} level 192 after exclusion) whether these 314 UC are excluded or not. To achieve a normal distribution of 193 the variable, we use the logarithm of the GDP p.c. in our analysis.

194 *Democracy*

195 The measure for democracy employed in our analysis is the Electoral democracy index by V-196 Dem. It consists of five sub-components that together capture Dahl's seven institutions of 197 polyarchy: freedom of association, suffrage, clean elections, elected executive, freedom of 198 expression, and alternative sources of information.⁴⁸ The resulting index ranges from 0 (low 199 performance) to 1 (best performance). We average V-Dem values between 2000 and 2015 and 200 consider a country as democratic when the V-Dem Electoral democracy index is > 0.5, and as 201 non-democratic if its rating is equal or below that value.

202 *Air pollution*

203 To measure air pollution, we use remote-sensed estimates of PM_{2.5} concentrations, expressed 204 in $\mu g/m^3$ as the total concentration of PM_{2.5}, averaged for every UC during the 2000-2016 205 period. This provides us with an exogenous measure of air pollution and a consistent scale around the globe. These remote-sensed estimates of PM_{2.5} are built from models that rely on 206 207 ground measurements, and thus carry more uncertainty in areas that do not have terrestrial AQM⁴². Nevertheless, because we average values over 17 years, we minimize potential biases 208 from monthly measurements. This is, to our knowledge, the most adequate data source of air 209 210 pollution available for our study and there are only two missing values for this variable in all 211 UCs in the dataset, both situated in Russia.

212 *Conflict*

To measure conflict, we use data from the UCDP/PRIO Armed Conflict Dataset, version 213 23.1.^{49,50} This dataset offers a range of information about conflict, including aspects such as 214 intensity, conflict type, and the start and end date of the conflict. Given that a conflict can 215 216 significantly shape the development of a whole country and considering the complexities of 217 aligning the conflict location with the UC dataset, we opt to incorporate the conflict variable at the national level and use it as a dummy variable that identifies if a conflict has resulted in over 218 219 1000 battle-related fatalities since its inception. As a country is also highly affected by the aftermath of war, the main variable considers any onset of a war from 2000 until 2022. 220

221 *Corruption*

222 To measure corruption within a country, we rely on the Corruption Perceptions Index (CPI), 223 created by Transparency International and use the average levels between 2012 to 2022. The 224 CPI ranks countries based on perceived public sector corruption, aggregating data from 225 different sources that reflect expert and business evaluations of public sector corruption. 226 Depending on the year in question, the index is formulated using roughly 12 distinct data sources, drawing upon various institutions that have recorded perceived corruption levels in 227 228 the respective country. The CPI is standardized on a scale from 0 to 100, ensuring year-to-year comparability. While within the index itself, a lower score signifies higher corruption and a 229 230 higher score indicates lower corruption, we adjust the variable so that a higher value denotes increased corruption, and a lower value signifies reduced corruption. This makes the 231 interpretation easier and simplifies comparisons across variables. 232

233 Other control variables

For control variables, we included the 2015 population size of each UC as an indicator of urbanization.⁵¹ Due to the significant skewness of this variable, we apply a logarithmic transformation before inclusion in the regression models. Additionally, we included a dummy variable that denotes whether an UC is the capital of a country.⁵¹ This variable is important as it is likely that many (monitoring) policies are first rolled out in a country's capital before being adopted in other urban areas. Additionally, we include dummy variables for China and India to control for fixed effects within the many UC in these countries.

241 Data Analysis

242 To explore the determinants underpinning monitoring behavior and address the outlined hypotheses, the initial approach uses bivariate analyses. This involves comparing mean values 243 244 across distinct groups, and significance tested with permutation tests because firstly, visual 245 inspection of the data revealed non-normality in the distribution of the groups, and secondly, unequal sample sizes can bias Welch tests towards lower p-values.⁵² We used the *perm* library⁵³ 246 247 with a Monte Carlo Approximation using 1'000 permutations. This approach is robust to non-248 normality and differences in sample sizes between two focal groups. To account for all 249 theoretically defined factors discussed earlier, including interactions between these factors, we employ two multivariate analyses. We model the presence (or absence) of at least one 250 251 monitoring station within an UC using binomial logistic regression. We also model the number of monitors in UCs, using a Poisson regression model⁵⁴, because of the zero-inflated nature of 252 253 our dataset, with most UCs not reporting AQM.

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 $\begin{array}{l} \text{Presence of AQM}_{it} = \beta_0 + \beta_1 GDPp. \, c. \, (log)_{it} + \beta_2 Democracy_{it} + \beta_3 PM2.5_{it} + \beta_4 PM2.5* Democracy_{it} + \\ \beta_5 Population(log)_{it} \beta_6 Conflict_{it} + \beta_7 Corruption_{it} + \beta_8 Capital_{it} + \beta_9 India_i + \beta_{10} China_i + \varepsilon_{it} \end{array}$

255 256

To assess the robustness of the results, we use different combinations of decisions 257 throughout the analysis and test them using multiverse analysis.⁵⁵ The multiverse package is 258 useful for adding transparency regarding methodological decision-making and its impact in the 259 260 analysis. The package offers a syntax that allows scientists to test consistency when using different combinations of methodological strategies, in an easy-to-test and report syntax, 261 262 instead of reporting one of them. While for the main analysis, we use a sub-sample for China 263 and India, 500 UCs each, we also run the regression using the complete dataset that includes 264 all UCs in China and India. In another regression, we exclude PurpleAir AQM stations, which 265 focus extensively on low-cost air sensors, thus the remaining dataset mainly contains referencegrade monitors. For another robustness check, we run the analysis with a second pollution dataset, the UC-level pollution dataset from "Urban Centre spatial domain based on Global Burden of Disease (GBD) 2017", derived from older remote-sensing estimates.⁴² Finally, we also run our analysis by including US embassy monitors. As Supplementary Figures. 1, 3, 4, and 6 show, none of these adjustments strongly influence our main finding.

We also test the sensitivity of findings to the random sub-sampling that we use to reduce the overrepresentation of China and India. To do that, we repeat our analysis 1000 times, each time selecting a different sample of the 500 UCs in China and India. We plot the coefficients of the interaction between pollution levels and non-democracy in Supplementary. Figure 6.

As we find that democracy influences AQM at the city level and democracy is a country-275 276 level variable, we model the number of monitors at the country level using a Poisson regression. 277 To do that, we use the country level variables such as corruption, conflict, and democracy, and 278 summed up the total number of monitors in UCs for each country, as well as the total population 279 living in UCs, the GDP p.c. at the country level, for the population in UCs, and the average pollution in UCs, for every country included in our analysis. The results show that our findings 280 281 are robust at the country level, with more democratic countries having more publicly reporting monitoring stations with increasing pollution, while non-democracies have more AQM if less 282 283 polluted.

284

285 Results

AQM activity in the cities of interest here is unevenly distributed around the world, with high monitoring density in China and India, and very low monitoring density in Africa and South America (Fig. 1). The three data platforms from which we extract locations of AQM provide varying coverage across different regions of the world, making it useful to include all three in our analysis (see Methods). There is little overlap between data from the air sensor provider PurpleAir and the two other data sources that focus more on Eastern Europe, China, and India.



Figure 1: Highly Uneven Geographic Distribution of AQM. Points on the map represent locations of AQM provided by the three data platforms we consider in our analysis (OpenAQ, WAQI, and PurpleAir). The histogram shows the number of monitors and overlaps for coverage by the three data platforms. Countries/areas excluded from the analysis (OECD and high-income countries) are coloured in grey.

China and India account for more than 2'100 and 380 monitors respectively, and over 298 299 1'800 and 3'100 cities respectively, with some cities among the most polluted globally (Fig. 2). This high concentration of AQM in China and India, and the high share of reference-grade 300 (as opposed to low-cost sensor) monitoring in these countries requires special attention when 301 exploring drivers of variation in AQM (see Methods). However, it is also worth noting that 302 China and India only rank 11th and 26th when normalizing the amount of AQM by urban 303 population (Fig. 2). Figure 2 also shows that a large share of AQM in China and India takes 304 place in cities experiencing medium to high levels of air pollution (remotely sensed). A much 305 306 larger share of AQM in cities of other countries focuses on areas with relatively low to medium pollution levels (again remotely sensed). Again, this implies that we need to pay 307 308 special attention to China and India when exploring the drivers of AQM, most notably how political systems and problem pressure act in combination. 309



Figure 2: Number of reference-grade and sensor (i.e. low cost)-based monitors per country (upper left) and per country
 normalized by population size, and number of cities with AQM in China, India, and other countries by pollution level.

- We now move to identifying the conditions under which we are likely to observe 313 AQM when comparing cities across the Majority World. Figure 3 offers some first, bivariate 314 315 insights. We are more likely to observe AQM in cities with higher income levels (p<0.01, permutation tests), while AQM activity does not seem to be associated with the level of 316 democracy (p > 0.32, permutation test). Less polluted cities are more likely to be monitored, 317 318 and cities in non-democratic settings tend to be more polluted (p < 0.01 & p < 0.01, permutation tests). Moreover, cities located in democracies that exhibit AQM are, on average, 319 significantly less polluted, while cities in non-democracies that exhibit AQM are, on average, 320 not significantly different in pollution levels (p < 0.01 and p = 0.054, permutation tests) from 321 322 those which do not monitor air quality. This observation aligns with the assertion that cities in 323 democratic settings are more responsive to increased air pollution, in the sense of engaging in 324 AQM.
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Figure 3: Potential drivers of variation in AQM activity. Dashed lines indicate the mean values for the explanatory variable
displayed in each graph, for cities with AQM (yellow) and those without (blue).

To better understand structural facilitators and obstacles to AQM, we control for confounders based on a regression analysis. Figure 4 shows predicted effect sizes for the main variables of interest (left side), and for a set of other factors (right side) frequently referred to in the literature on AQM.

The results indicate that AQM is more likely to be present in cities that are (within the 333 334 income range of the countries we consider) wealthier, located in more democratic countries, 335 and have higher pollution levels, particularly in democracies. This means that more polluted 336 cities in democracies are more likely to have AQM than similarly polluted cities in nondemocracies. Cities in countries where there is a war also exhibit a higher likelihood of 337 338 AQM. Larger populations and capital city status increase the probability of AQM as well. Conversely, high corruption levels reduce the likelihood of AQM. The results differentiated 339 for reference-grade and (low-cost) sensor-based AQM are shown in the appendix in 340 Supplementary Figure 1. 341 342



Figure 4: Effects of explanatory variables. The marginal effects are calculated by fixing a variable at a specific value and running predictions in the model, keeping all other variables at their observed average values. Marginal effects for continuous variables are calculated at the first (in the figure referred to as 'low') and third (referred to as 'high') quartiles of the observed distribution. Categorical variables' marginal effects are calculated for both levels of each variable (e.g. 'At war' vs 'Not at war'). The model building the ground for this figure is a binary logit regression that includes the variables listed in the figure.

349 Adding further evidence for the democratic responsiveness argument, Figure 5 shows how the predicted probability of AQM being present changes with increasing pollution levels 350 351 for cities in democratic and non-democratic countries (pollution levels are again captured with remote sensing data to avoid endogeneity bias). Supplementary Figure 2 in the appendix 352 353 shows the same interaction effect for different economic contexts. It shows that this interaction effect materializes mainly in economic contexts other than very low and very 354 high-income settings. Irrespective of democracy, very poor cities have a very low predicted 355 356 probability of AQM being present, and very rich cities in our sample have a very high 357 probability, even if they are moderately polluted.



Figure 5: Predicted probability of AQM relative to pollution levels (PM_{2.5}) from 2000-2016 in cities located within a
 democratic or non-democratic setting. The model pictured here is the same binary logit regression model as in Figure 4. It
 includes all variables described in the methods part. The variables not shown in the graph are set to the mean of the
 observed values. The grey histogram shows the distribution of the pollution levels across the cities included in the
 regression.

We examined the robustness of our main findings in several ways. These include using a different dataset for remotely sensed air pollution ("Urban Centre spatial domain based on Global Burden of Disease (GBD) 2017 data"), different random sub-samples of cities in China and India, data for all cities including those in China and India, excluding AQM activity captured with data from air sensors of PurpleAir, and including or excluding AQM by US embassies (Supplementary Fig. 3).

371 The results indicate that the presence of AQM is associated with higher pollution 372 levels in cities within democratic settings. Although the effect is weaker for reference-grade 373 monitors, it remains statistically significant when applying what we consider the most 374 appropriate estimation strategy (Fig. 6). The effects remain significant when using a Poisson regression to predict the number of monitors (rather than the presence or absence of 375 AQM), accounting for the zero-inflated distribution of AQM, with robust results across 376 different regression models and datasets (Supplementary Fig. 4). Because democracy is 377 378 ultimately a country-level variable, we also conduct a Poisson regression analysis to predict 379 the number of monitors in each country based on the average income level, population, and 380 air pollution levels of all cities in a given country. We find similar results with weaker statistical significance (Supplementary Fig. 5 and Supplementary Table 1). Finally, we 381 382 examined whether the presence of US embassy-based AQM may crowd in or crowd out other

383 AQM in the respective city. We find that when controlling for other factors, such as income,

- 384 population, and democracy, there are fewer reference-grade monitors, and more air sensors,
- in capital cities that host a US embassy monitor, but find no effect when not differentiating
- 386 monitor type (Supplementary Table 2).



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Figure 6: Robustness of main results. This figure shows that the main pattern of how AQM activity behaves with increasing
 pollution levels in democratic and non-democratic settings remains similar when using different data sources for remotely
 sensed pollution, including all cities or downsized samples for China and India, including only reference-grade or low-cost
 air sensor AQM or both, and including or excluding AQM by embassies. Numbers on the top right of each graph display the
 effect size of the interaction term between democracy and pollution, along with its significance level. The graph in the black
 frame corresponds to the main analysis that is displayed in Figure 5.

394

395 Discussion

Air pollution constitutes a major public health challenge worldwide, particularly so in urban areas of the Majority World. Air quality monitoring is as an important tool for making progress towards cleaner air. Remote sensing data is increasingly available, but ground-level estimates of air pollution levels still need to be calibrated with data from on-site monitoring, and regulatory monitoring still relies on reference-grade monitors. Indeed, the spatial and temporal resolution of remote sensing data on urban air pollution is still inadequate for localized action in terms of identifying pollution hotspots, building public awareness,

403 enforcing regulations, tracking progress, and ultimately reducing pollution levels.

The present paper is, to our knowledge, the first to describe variation in AQM across all cities 405 in the Majority World and explore potential drivers of such variation. Besides observing a 406 407 glaring gap in AQM across a vast part of the urban Majority World, our analysis highlights 408 economic and political conditions as key drivers of variation in AQM. While the positive 409 effect of income levels on AQM probably lines up with common intuition, the fact that the 410 effect of increasing pollution levels is contingent on democracy is in our view quite 411 intriguing. All else equal, public authorities in more democratic settings appear to be more responsive to increasing pollution levels, probably both by engaging and allowing others to 412 engage in more reference-type and low-cost sensor-based AQM. Differences between 413 reference-grade and low-cost sensors suggest that in non-democracies, governments set up 414 one reference-grade station and commonly leave it at that, whereas low-cost sensors 415 416 proliferate particularly in highly polluted areas of the democratic Majority World. Our 417 observation that non-democracies are more likely to monitor in lower pollution areas also 418 suggests that the choices of monitoring locations are politically biased.

419 While providing a wake-up call for public authorities, international institutions, and civil society stakeholders to invest far more than hitherto the case into AQM, particularly in 420 421 under-monitored poorer, and less democratic settings, our research also points to various 422 interesting avenues for further research. Focusing in greater depth on the cities with 423 (currently) observable AQM could provide interesting insights into variation in the spatial and temporal density as well as pollutant coverage of monitoring, variation in how public 424 425 authorities and other actors are making pollution data public, and which efforts are made (or 426 not made) to improve monitoring networks. Such work could also examine whether there are 427 socio-economic biases in AQM, e.g. more monitoring in more affluent areas of a city, and 428 vice versa. It could also study the conditions under which improvements could be achieved 429 with low-cost sensors that are operated by both governments and independent actors (private individuals, NGOs, companies engaging in transparency). In identifying AQM activity, 430 431 further research could also investigate potential biases when picking up AQM from reported 432 pollution data. If, as one might suspect, non-democratic regimes measure air pollution, but 433 withhold the data from the public to avoid criticism, this could explain why cities in 434 democratic settings seem to be more responsive to high levels of air pollution. The fact that our data identifies AQM activity in non-democratic settings implies that such bias is probably 435 436 limited. Nevertheless, more work is needed to understand underlying mechanisms leading to the limited extent of AQM in most polluted non-democracies. 437

439	We believe that AQM and environmental monitoring in other domains for that matter,	
440	are a key element in societal efforts aimed at improving environmental conditions and	
441	deserve more scientific attention than is currently the case. We thus hope that the present	
442	paper encourages others to explore further the inferences we can draw from reported	
443	environmental data for the preferences and behavior of public authorities and other	
444	stakeholders.	
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